

# CS483-11 Transform-and-Conquer

Instructor: Fei Li

Room 443 ST II

Office hours: **Tue. & Thur. 1:30pm - 2:30pm** or by appointments

`lifei@cs.gmu.edu` with **subject: CS483**

[http://www.cs.gmu.edu/~lifei/teaching/cs483\\_fall07/](http://www.cs.gmu.edu/~lifei/teaching/cs483_fall07/)

Based on *Introduction to the Design and Analysis of Algorithms* by Anany Levitin and Professor

Jyh-Ming Lien's notes.

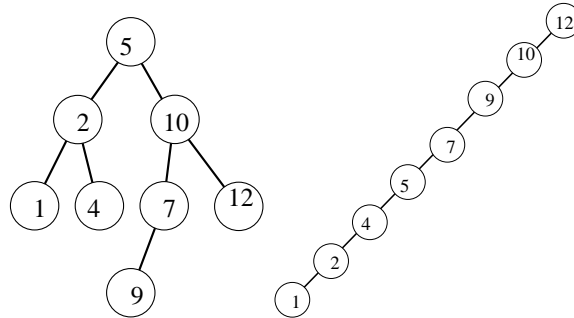
## Outline

- ▶ Transform and Conquer Techniques (which allow us to handle **dynamic** data / information)
  - **Binary search tree**
  - AVL tree via **rotations** (or red-black tree or splay tree)
  - 2 – 3 tree (or 2 – 3 – 4 tree or  $B$  tree)
  - Heap

## Binary Search Tree

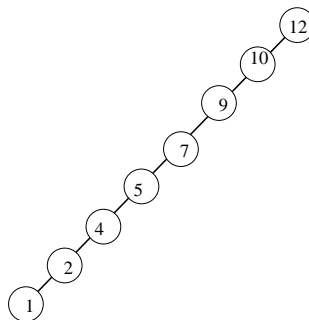
► **Binary search tree** is a **binary tree** each of whose nodes  $n$  has the following properties:

- All values in the **left sub-tree** are **smaller** than the value of  $n$
- All values in the **right sub-tree** are **larger** than the value of  $n$



## Binary Search Tree

- What's the advantage of a binary search tree over an array or a list?
- Efficient related searching and sorting algorithms
  - Inorder traversal produces sorted list
- We can search and **dynamically insert a value** and **delete a node** from binary search tree.
- Unfortunately, the worst case of these operation can have time complexity:  $O(n)$ , when the tree becomes a list



## Balanced Search Trees

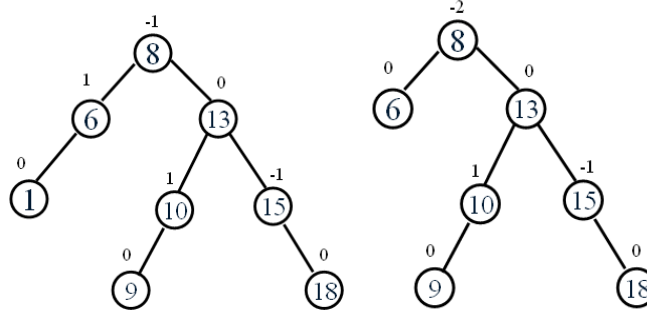
- ▶ Attractiveness of binary search tree is blurred by the bad (linear) worst-case efficiency.
- ▶ Two ways to solve this:
  - To **rebalance** binary search tree when a new insertion makes the tree “too unbalanced”
    - **AVL trees**
    - red-black trees
  - To allow **more than one key per node** of a search tree
    - **2 – 3 trees**
    - 2 – 3 – 4 trees
    - *B*-trees

## Outline

- ▶ Transform and Conquer Techniques (which allow us to handle **dynamic** data / information)
  - Binary search tree
  - **AVL tree via rotations** (or red-black tree or splay tree)
  - 2 – 3 tree (or 2 – 3 – 4 tree or *B* tree)
  - Heap

## AVL Tree

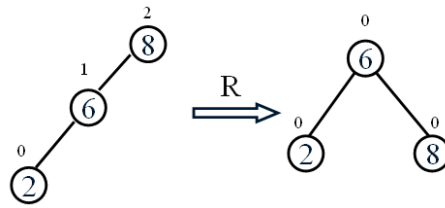
- ▶ AVL tree (named after G.M. Adelson-Velsky and E.M. Landis) is always a **balanced** binary search tree.
- ▶ **Balance factor** of a node  $n$ : the **difference between the heights of  $n$ 's left and right sub-tree**.
- ▶ The **balance factor** of every node in an AVL tree must be either  $-1$ ,  $0$ , or  $+1$ . The height of an empty tree defined as  $-1$ .



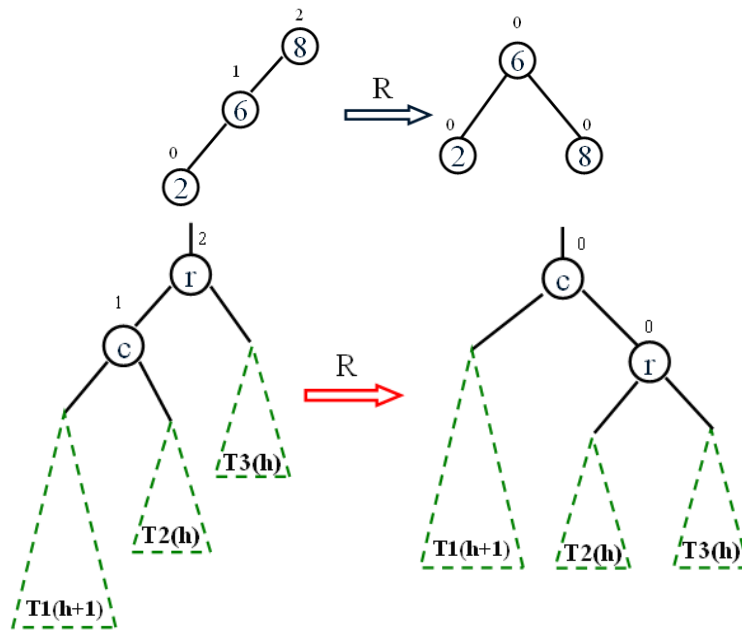
## AVL Tree

- ▶ AVL tree **rotates nodes** to maintain the balance **after a node is added or removed** from the tree.
- ▶ **Rotation** is performed for a subtree rooted at the **lowest unbalanced node**.
- ▶ There are four types of rotations: L-rotation, R-rotation (single rotations), LR-rotation, RL-rotation (double rotations)

Case 1: R rotation

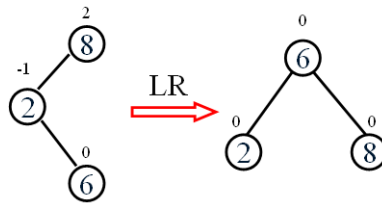


Case 1: R rotation

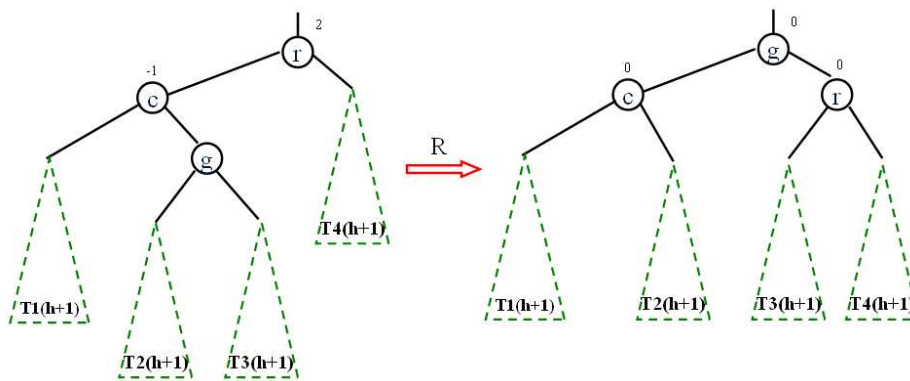
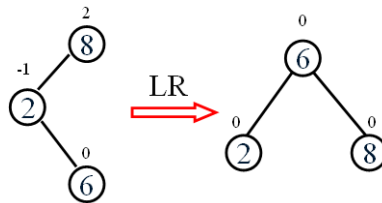


Case 2: L rotation

**Case 3: LR rotation**



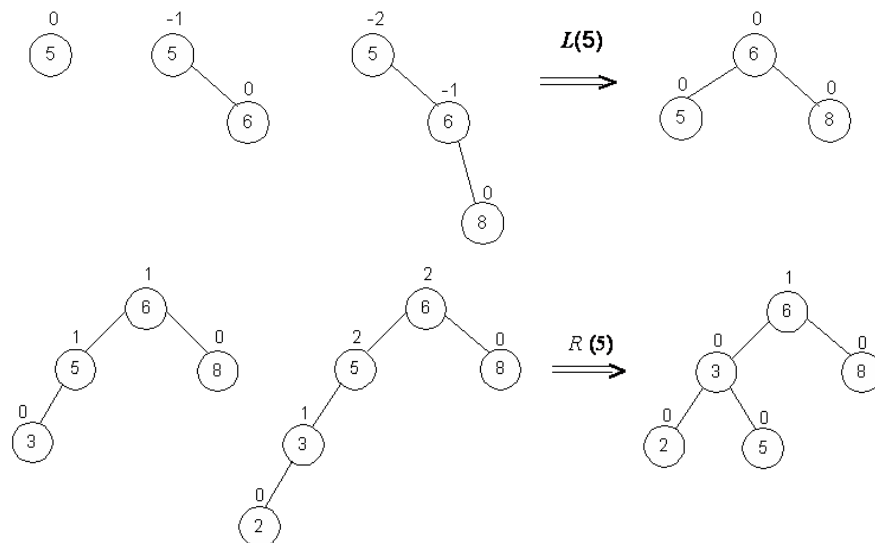
**Case 3: LR rotation**



Case 4: RL rotation

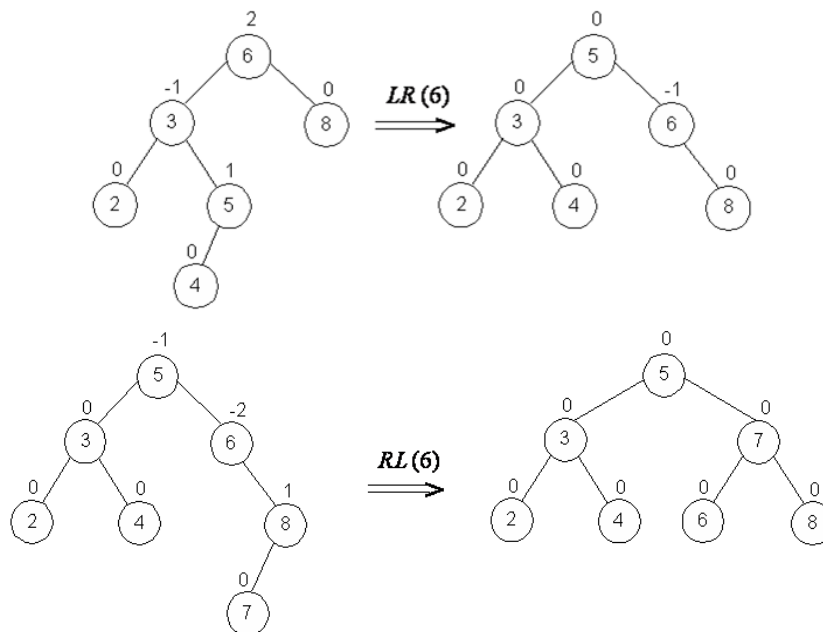
### AVL Tree Construction - Example

Build an AVL tree from the list {5, 6, 8, 3, 2, 4, 7}



### AVL Tree Construction - Example

Build an AVL tree from the list {5, 6, 8, 3, 2, 4, 7}



## AVL Tree Analysis

- ▶ What is the height  $h$  of any AVL tree with  $n$  nodes?
  - $h \leq 1.4404 \log_2(n + 2) - 1.3277$
  - Average height:  $1.01 \log_2 n + 0.1$  for large  $n$  (found empirically)

## AVL Tree Analysis

- ▶ What is the height  $h$  of any AVL tree with  $n$  nodes?
  - $h \leq 1.4404 \log_2(n + 2) - 1.3277$
  - Average height:  $1.01 \log_2 n + 0.1$  for large  $n$  (found empirically)
- ▶ What is the time complexity of the  $R$ -,  $L$ -,  $LR$ -, or  $RL$ -rotations?
- ▶ What is the time complexity of search/insert/delete of AVL tree?



## AVL Tree Analysis

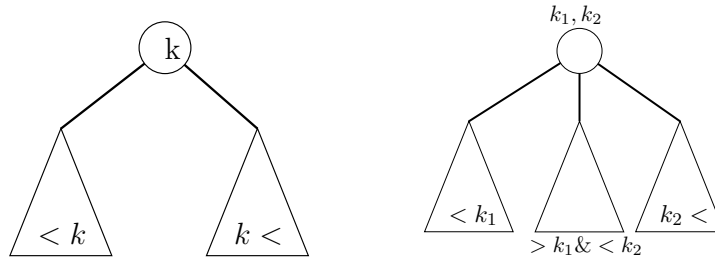
- ▶ What is the height  $h$  of any AVL tree with  $n$  nodes?
  - $h \leq 1.4404 \log_2(n + 2) - 1.3277$
  - Average height:  $1.01 \log_2 n + 0.1$  for large  $n$  (found empirically)
- ▶ What is the time complexity of the  $R$ -,  $L$ -,  $LR$ -, or  $RL$ -rotations?  
 $O(1)$
- ▶ What is the time complexity of search/insert/delete of AVL tree?  
 $O(\log n)$
- ▶ Disadvantages:
  - Frequent rotations
  - Complexity

## Outline

- ▶ Transform and Conquer Techniques (which allow us to handle **dynamic** data / information)
  - Binary search tree
  - AVL tree via **rotations** (or red-black tree or splay tree)
  - **2 – 3 tree (or 2 – 3 – 4 tree or  $B$  tree)**
  - Heap

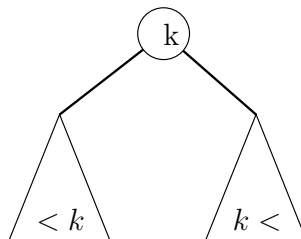
## 2 – 3 Tree

- A 2 – 3 tree is a search tree in which
- Each node can have **two or three kids** (with one or two keys);
  - **Height-balanced** (all leaves of the tree are at the same level).



## 2-3 Tree

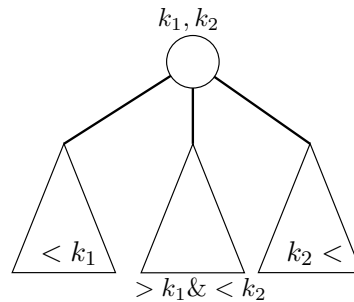
- For a node with **two kids**, the node has one key. All the keys in the **left** (resp., **right**) sub-tree are **smaller** (resp., **larger**) than the key of the node.



## 2 – 3 Tree

- ▶ For a node with **three kids**, the node has **two keys**. All the keys in the **left** (resp., **right**) sub-tree are **smaller** (resp., **larger**) than the **first** (resp., **second**) keys of the node.

The keys in the **middle** tree have values **between the first and second key**.



## Building a 2 – 3 Tree

- ▶ Iteratively insert the values in to the tree
  - If the tree is **empty**, **create a node** with the value
  - Otherwise, **search a leaf**  $n$  that  $v$  can be put into and put  $v$  to  $n$ :
    1. If the **size** of  $n$  is **three**, make the node into to a **2-node sub-tree**  $T$ .
    2. **Insert the root of**  $T$  **into**  $n$ 's parent node.
    3. Repeat step 1 and 2 for  $n$ 's parent
- ▶ Example: Build a 2 – 3 tree from the list  $\{9, 5, 8, 3, 2, 4, 7\}$ 

Answer is in the book.

### Analyzing a 2 – 3 Tree

- ▶ What is the height of a 2 – 3 Tree with  $n$  nodes?

$$\log_3(n + 1) - 1 \leq h \leq \log_2(n + 1) - 1$$

- ▶ What is the time complexity of each insertion, search, and delete?

$$O(\log n)$$