

CS483-11 Transform-and-Conquer

Instructor: Fei Li

Room 443 ST II

Office hours: **Tue. & Thur. 1:30pm - 2:30pm** or by appointments

`lifei@cs.gmu.edu` with **subject: CS483**

`http://www.cs.gmu.edu/~lifei/teaching/cs483_fall07/`

Based on *Introduction to the Design and Analysis of Algorithms* by Anany Levitin and Professor

Jyh-Ming Lien's notes.

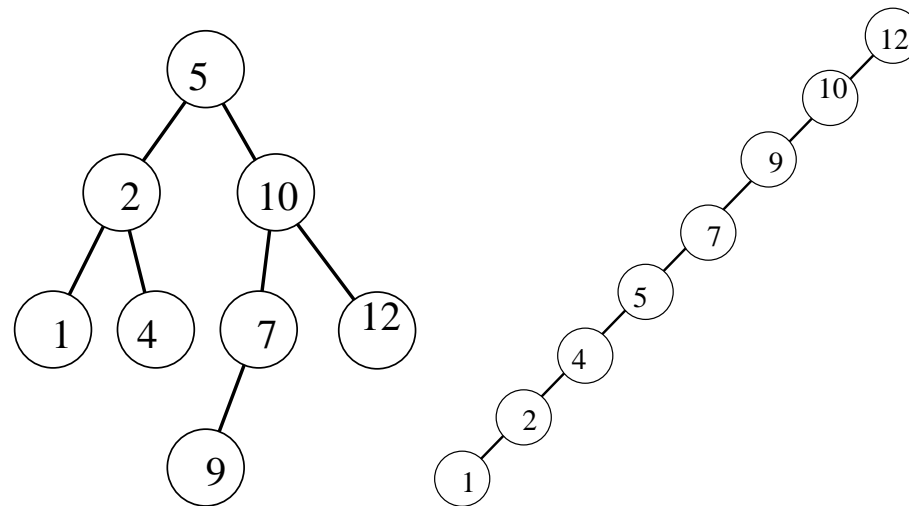
Outline

- Transform and Conquer Techniques (which allow us to handle **dynamic** data / information)
 - Binary search tree
 - AVL tree via **rotations** (or red-black tree or splay tree)
 - 2 – 3 tree (or 2 – 3 – 4 tree or *B* tree)
 - Heap

Binary Search Tree

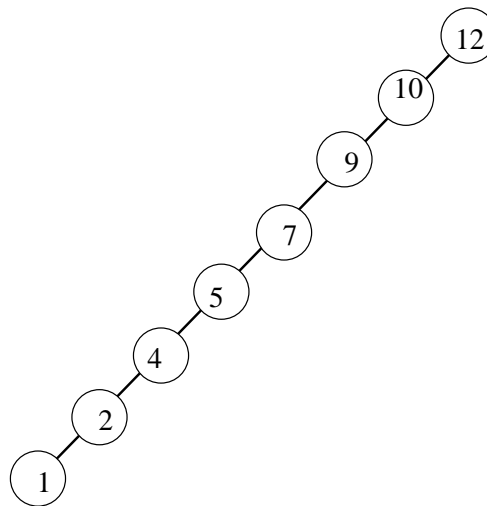
➤ **Binary search tree** is a **binary tree** each of whose nodes n has the following properties:

- All values in the **left sub-tree** are **smaller** than the value of n
- All values in the **right sub-tree** are **larger** than the value of n



Binary Search Tree

- What's the advantage of a binary search tree over an array or a list?
 - Efficient related searching and sorting algorithms
 - Inorder traversal produces sorted list
- We can search and **dynamically insert a value** and **delete a node** from binary search tree.
- Unfortunately, the worst case of these operation can have time complexity: $O(n)$, when the tree becomes a list



Balanced Search Trees

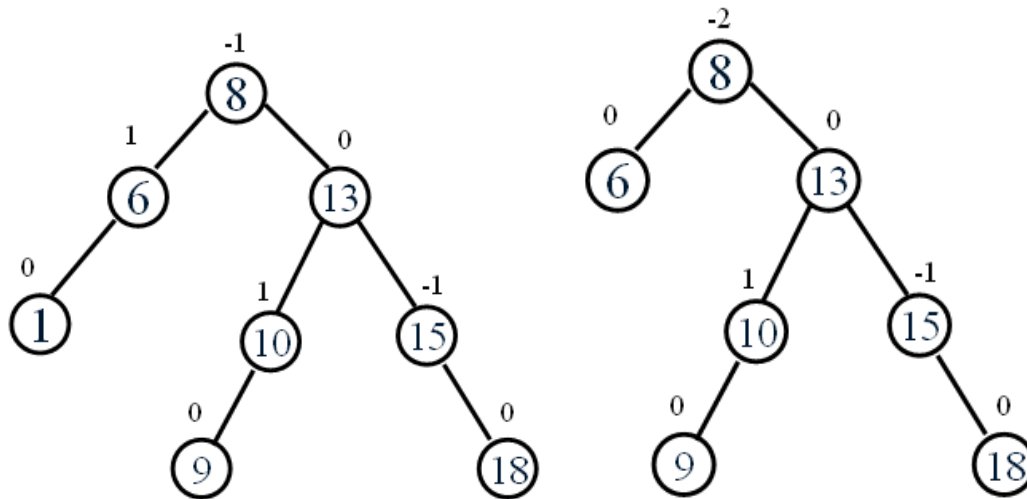
- Attractiveness of binary search tree is blurred by the bad (linear) worst-case efficiency.
- Two ways to solve this:
 - To **rebalance** binary search tree when a new insertion makes the tree “too unbalanced”
 - **AVL trees**
 - red-black trees
 - To allow **more than one key per node** of a search tree
 - **2 – 3 trees**
 - 2 – 3 – 4 trees
 - *B*-trees

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AVL Tree

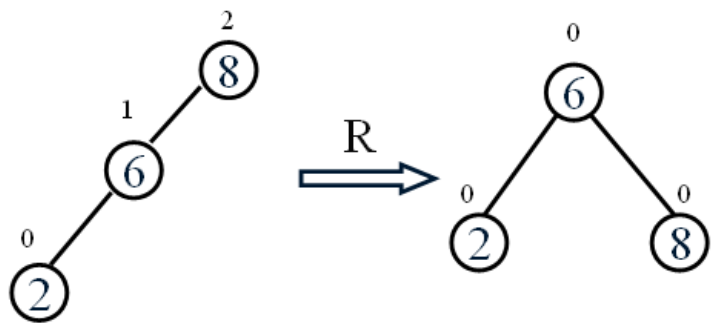
- AVL tree (named after G.M. Adelson-Velsky and E.M. Landis) is always a **balanced** binary search tree.
- **Balance factor** of a node n : the **difference between the heights of n 's left and right sub-tree**.
- The **balance factor** of every node in an AVL tree must be either -1 , 0 , or $+1$. The height of an empty tree defined as -1 .



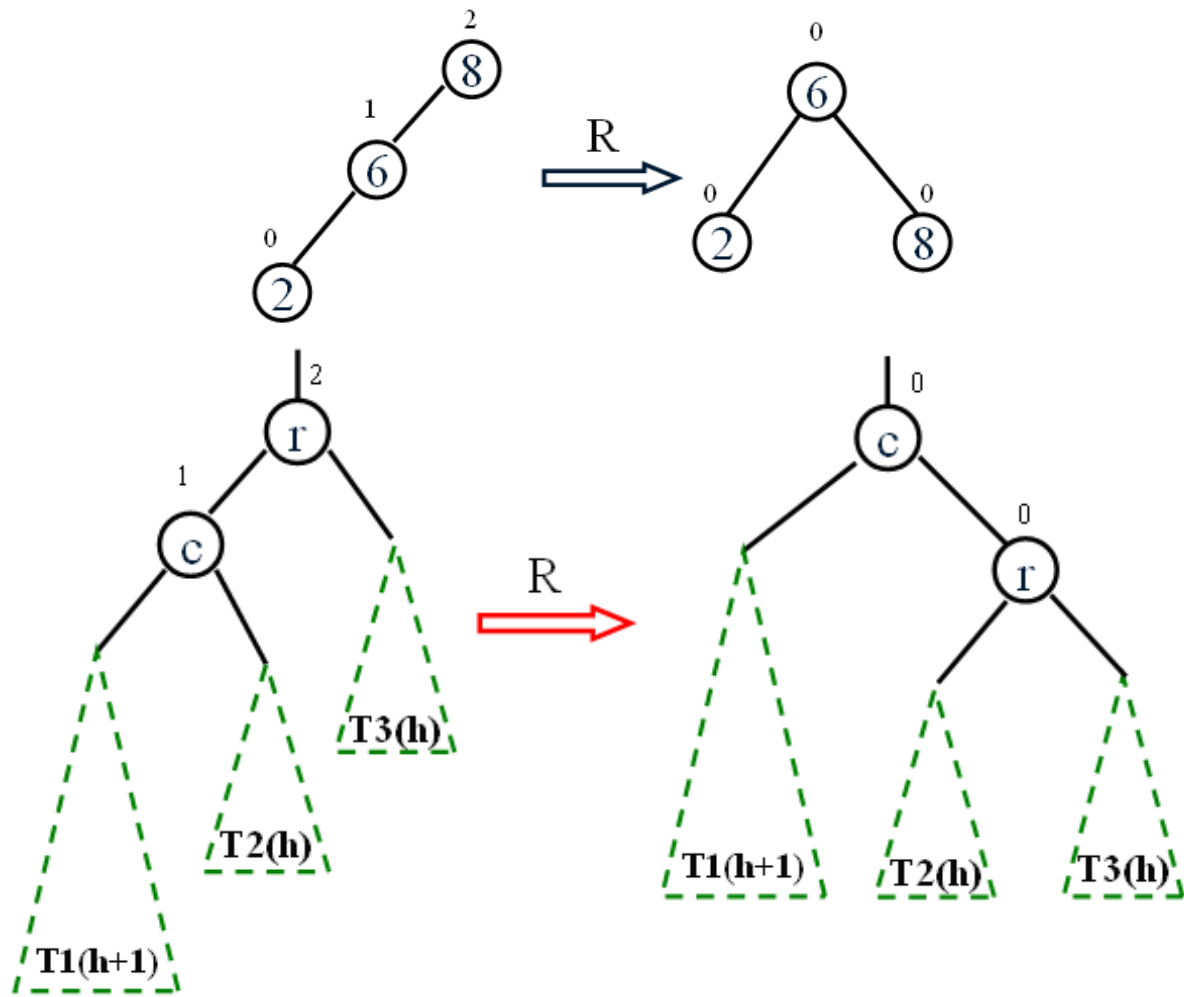
AVL Tree

- AVL tree **rotates nodes** to maintain the balance **after a node is added or removed** from the tree.
- **Rotation** is performed for a subtree rooted at the **lowest unbalanced node**.
- There are four types of rotations: L-rotation, R-rotation (single rotations), LR-rotation, RL-rotation (double rotations)

Case 1: R rotation

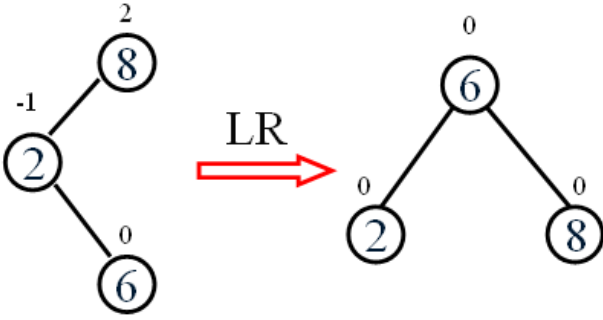


Case 1: R rotation

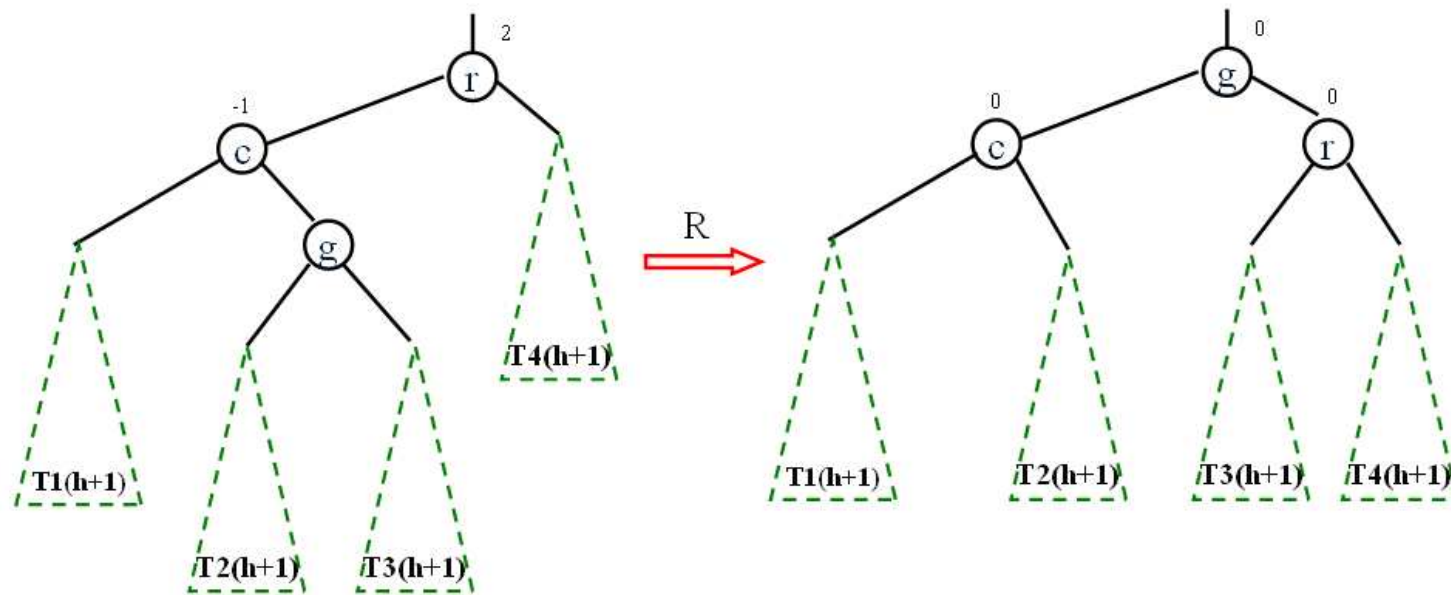
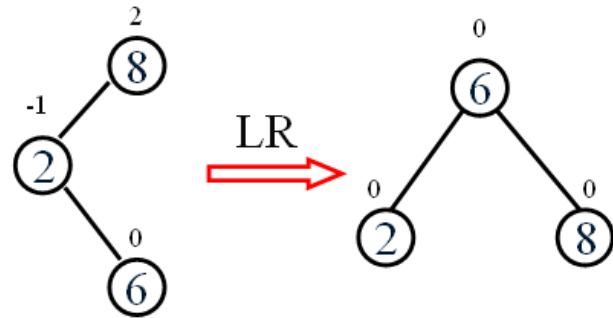


Case 2: L rotation

Case 3: LR rotation



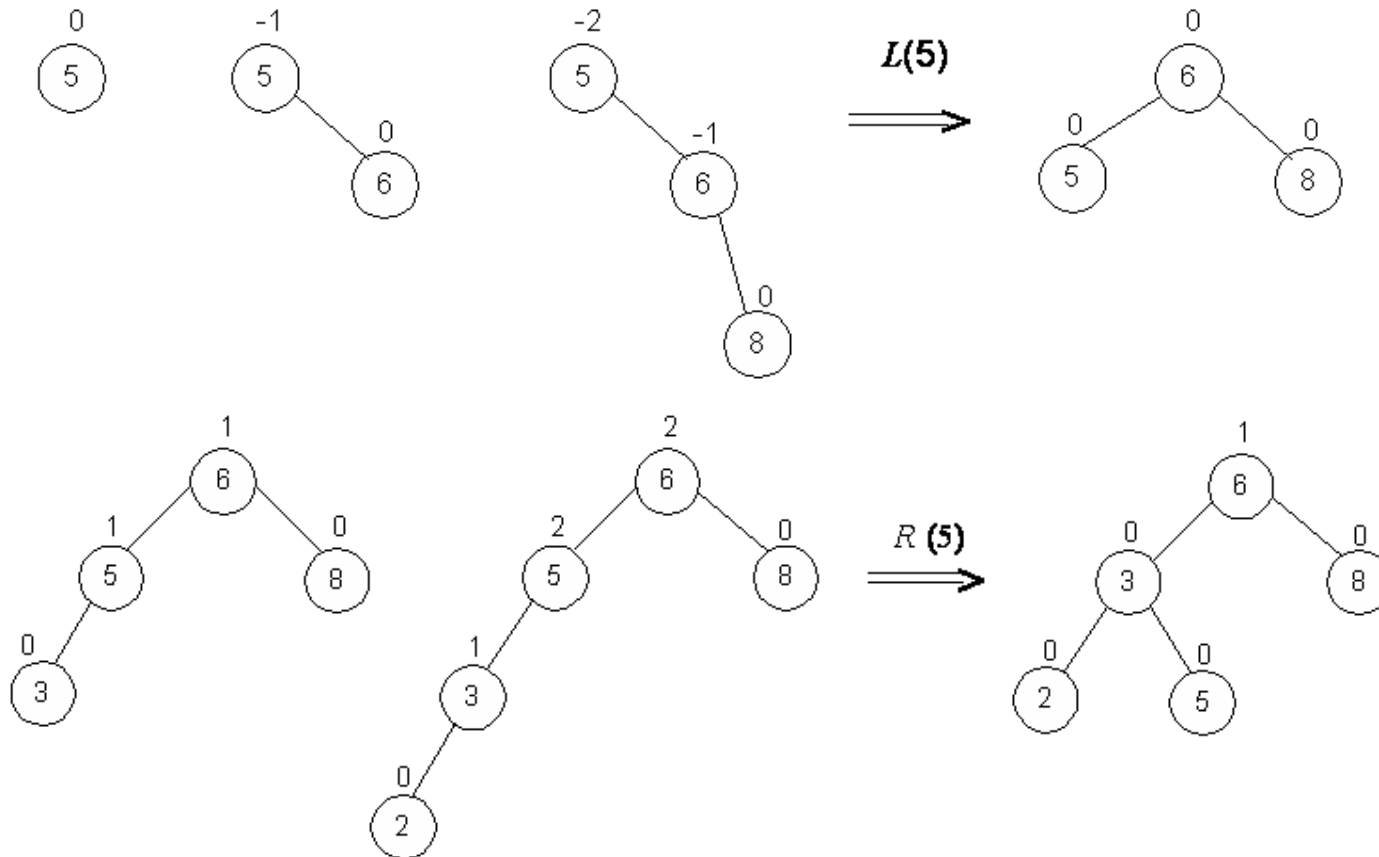
Case 3: LR rotation



Case 4: RL rotation

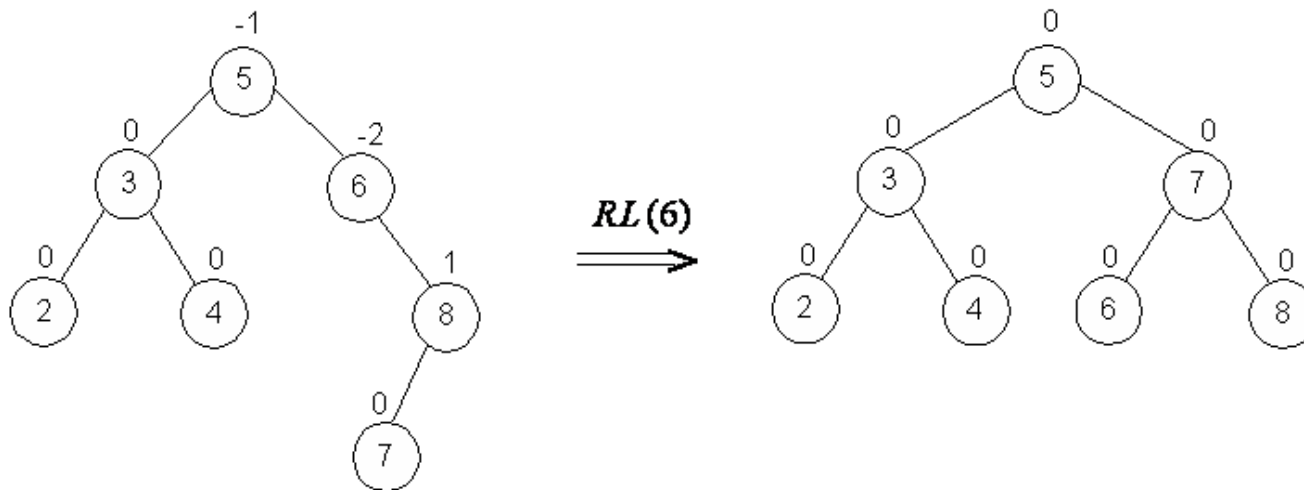
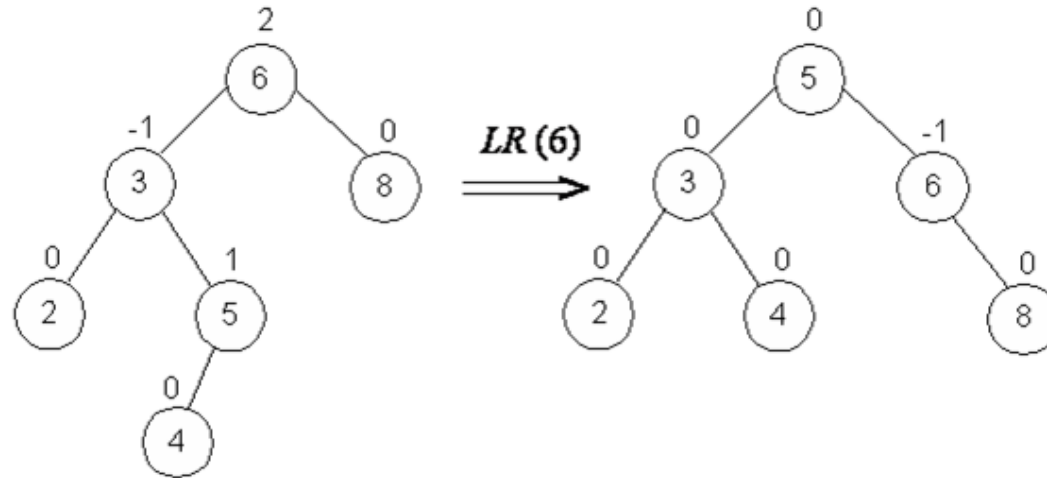
AVL Tree Construction - Example

Build an AVL tree from the list {5, 6, 8, 3, 2, 4, 7}



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AVL Tree Analysis

- What is the **height** h of any **AVL tree with n nodes**?
- $h \leq 1.4404 \log_2(n + 2) - 1.3277$
 - Average height: $1.01 \log_2 n + 0.1$ for large n (found empirically)

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AVL Tree Analysis

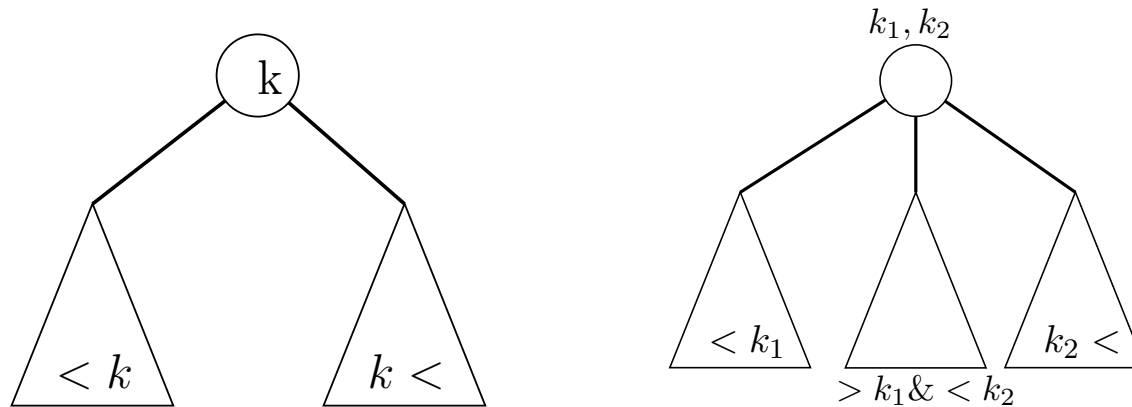
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- What is the time complexity of the R -, L -, LR -, or RL -rotations?
 $O(1)$
- What is the time complexity of search/insert/delete of AVL tree?
 $O(\log n)$
- Disadvantages:
 - Frequent rotations
 - Complexity

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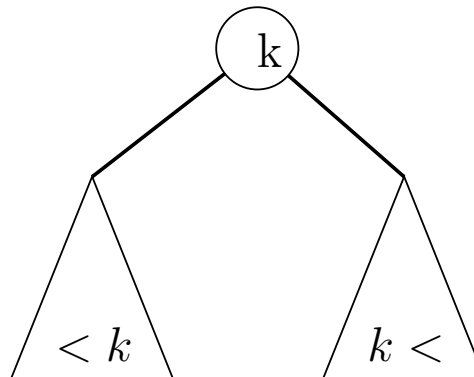
2 – 3 Tree

- A 2 – 3 tree is a search tree in which
- Each node can have **two or three kids** (with one or two keys);
 - **Height-balanced** (all leaves of the tree are at the same level).



2-3 Tree

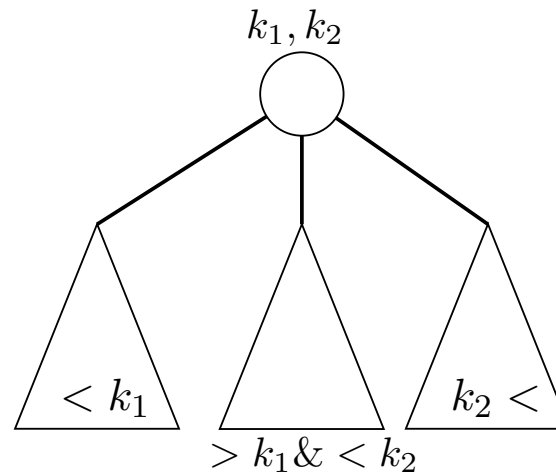
- For a node with **two kids**, the node has one key. All the keys in the **left** (resp., **right**) sub-tree are **smaller** (resp., **larger**) than the key of the node.



2 – 3 Tree

- For a node with **three kids**, the node has **two keys**. All the keys in the **left** (resp., **right**) sub-tree are **smaller** (resp., **larger**) than the **first** (resp., **second**) keys of the node.

The keys in the **middle** tree have values **between the first and second key**.



Building a 2 – 3 Tree

- Iteratively insert the values in to the tree
 - If the tree is empty, create a node with the value
 - Otherwise, search a leaf n that v can be put into and put v to n :
 1. If the size of n is three, make the node into to a 2-node sub-tree T .
 2. Insert the root of T into n 's parent node.
 3. Repeat step 1 and 2 for n 's parent
- Example: Build a 2 – 3 tree from the list $\{9, 5, 8, 3, 2, 4, 7\}$

Answer is in the book.

Analyzing a 2 – 3 Tree

- What is the height of a 2 – 3 Tree with n nodes?

$$\log_3(n + 1) - 1 \leq h \leq \log_2(n + 1) - 1$$

- What is the time complexity of each insertion, search, and delete?

$$O(\log n)$$