

# CS483-09 Elementary Graph Algorithms

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Office hours: **Tue. & Thur. 1:30pm - 2:30pm** or by appointments

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[http://www.cs.gmu.edu/~lifei/teaching/cs483\\_fall07/](http://www.cs.gmu.edu/~lifei/teaching/cs483_fall07/)

Based on "Introduction to Algorithms" by T. Cormen, C. Leiserson, R. Rivest, and C. Stein and  
"Algorithms" by S. Dasgupta, C. Papadimitriou, and U. Vazirani.

## Outline

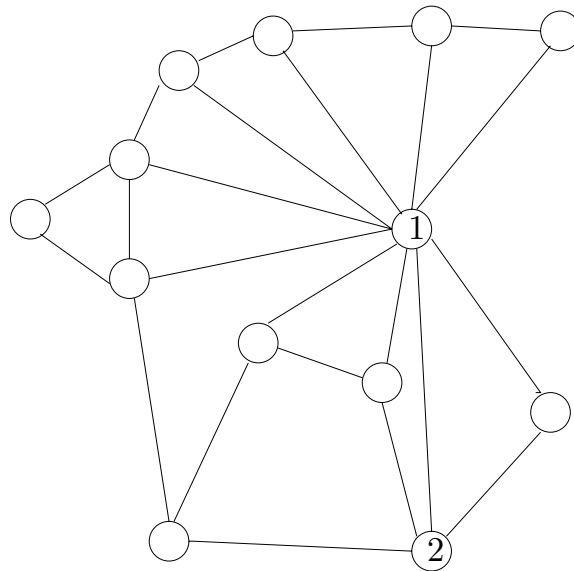
- ▶ **Representation of Graphs**
- ▶ Breath-first Search
- ▶ Depth-first Search
- ▶ Topological Sort

## Why Graphs?



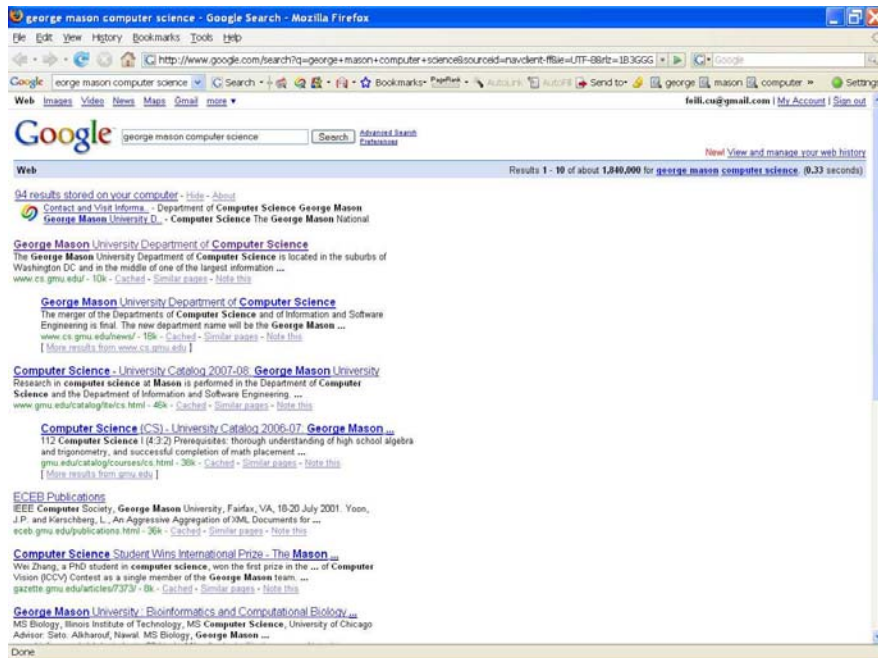
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## Why Graphs?



1 Brazil  
2 Argentina

## Why Graphs?



## Why Graphs?

<http://adcentered.typepad.com> is:  5



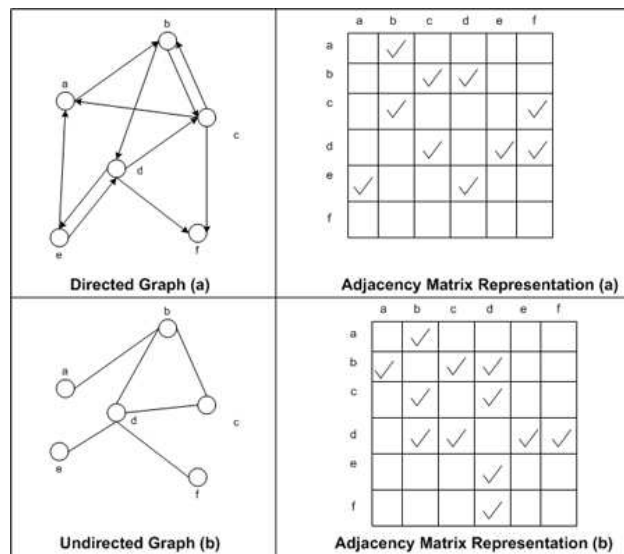
<http://adcentered.typepad.com/photos>

## Graphs

- ▶ A graph  $G = (V, E)$  is specified by a set of vertices (nodes)  $V$  and edges  $E$  between selected pairs of vertices.
- ▶ Edges are symmetric — *undirected graph*
- ▶ Directions over edges — *directed graph*
- ▶ Examples: political maps, exam conflicts, World Wide Web, etc.

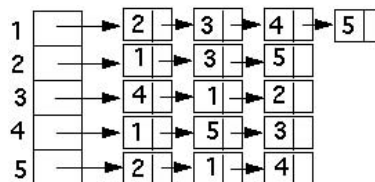
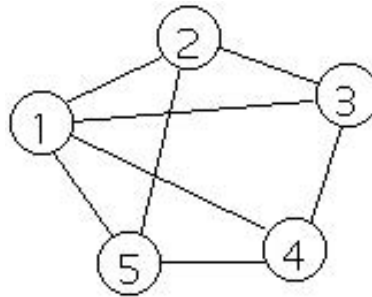
## Graph Representation

- ▶ Adjacency-matrix



## Graph Representation

► Adjacency-list



## Graph Traversal is Important

Exploring a graph is rather like navigating a maze.

Which parts of the graph are reachable from a given vertex?



<http://www.sheffordtown.co.uk/maze/index.html>

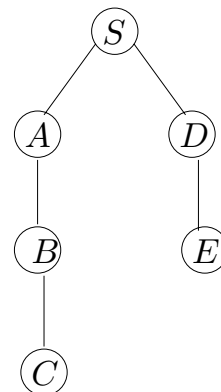
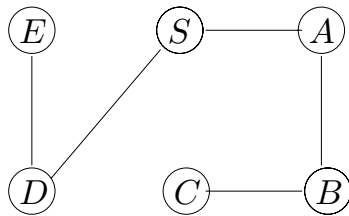
## Outline

- ▶ Representation of Graphs
- ▶ **Breadth-first Search**
- ▶ Depth-first Search
- ▶ Topological Sort

## Breadth-first Search (BFS)

BFS

1. **Identifies** all the **vertices** of a graph that can be **reached** from a designated starting point, and
2. **Finds** explicit **paths** via a **depth-first search tree**.



## Breadth-first Search (BFS)

**Input:** Graph  $G = (V, E)$ , directed or undirected; vertex  $s \in V$

**Output:** For all vertices  $u$  reachable from  $s$ ,  $d(u)$  is set to the distance from  $s$  to  $u$

**Intuition:** Proceed layer by layer

**Algorithm 0.1:**  $\text{BFS}(G, s)$

**for**  $\forall u \in V$

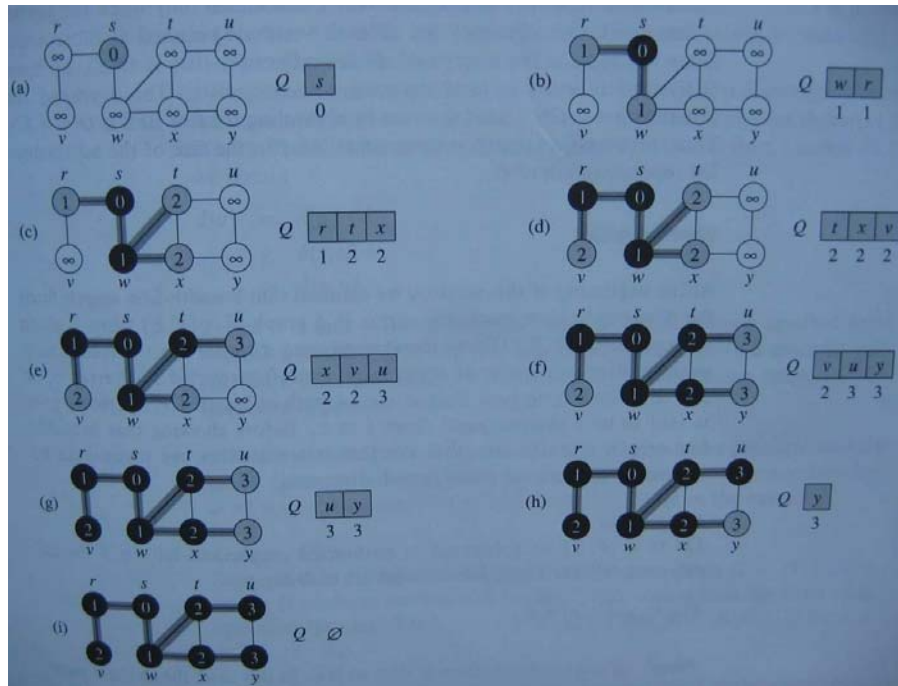
$d(u) = \infty$

$d(s) = 0$

$Q = [s]$

**while**  $Q \neq \emptyset$

$\left\{ \begin{array}{l} u = \text{Pop}(Q) \\ \text{for } (u, v) \in E \\ \left\{ \begin{array}{l} \text{if } d(v) = \infty \\ \text{then } \left\{ \begin{array}{l} \text{Push}(Q, v) \\ d(v) = d(u) + 1 \end{array} \right. \end{array} \right. \end{array} \right.$



### Breadth-first Search (BFS)

- The **correctness proof**: Use an induction method
- The overall **running time** of *BFS* is  $O(|V| + |E|)$ .
  - Each vertex is put on the queue exactly once, when it is first encountered, so there are  $2 \cdot |V|$  queue operations.
  - Over the course of execution, this loop **looks at each edge** once (in directed graphs) or twice (in undirected graphs), and therefore takes  $O(|E|)$  time.



## Outline

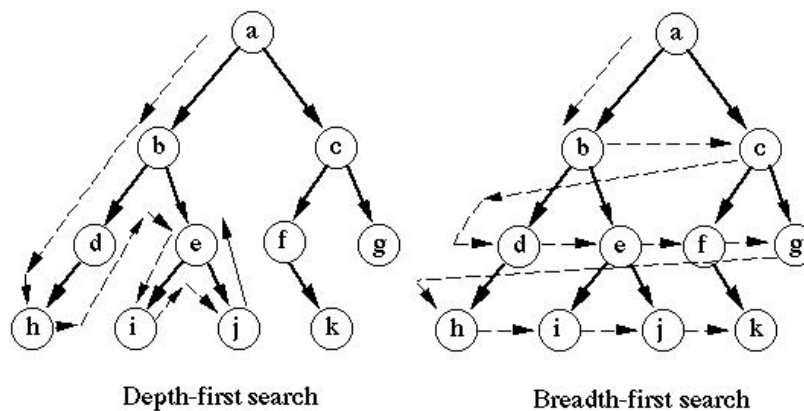
- ▶ Representation of Graphs
- ▶ Breath-first Search
- ▶ **Depth-first Search**
- ▶ Topological Sort

## Depth-first Search

**Input:** Graph  $G = (V, E)$ , directed or undirected; vertex  $s \in V$

**Output:** All vertices  $u$  reachable from  $s$  in timestamps of visiting

**Intuition:** Explore each vertex as much as you can



## Depth-first Search (DFS)

$\pi[u]$ : the parent of a node  $u$ .

$time[u]$ : timestamp when  $u$  is first discovered.

**Algorithm 0.2:** DFS( $G(V, E)$ )

**for** each vertex  $u \in V(G)$

**do** color[ $u$ ]  $\leftarrow$  WHITE

$\pi[u] \leftarrow$  NIL

time  $\leftarrow$  0

**for** each vertex  $u \in V(G)$

**do if** color[ $u$ ] = WHITE

**then** DFS-VISIT( $u$ )

**Algorithm 0.3:** DFS-VISIT( $u$ )

```
color[u] ← GRAY
//White vertex u has just been discovered.
d[u] ← time ← time + 1
for each  $v \in \text{Adj}[u]$ 
  //Explore edge  $(u, v)$ .
  {
    do if color[v] = WHITE
    {
      then  $\pi(v) \leftarrow u$ 
      DFS-VISIT( $v$ )
    }
  }
color[u] ← BLACK
//Blacken u; it is finished.
d[u] ← time ← time + 1
```

