



- Plot the eigenvalues each eigenvalue is related to the amount of variation explained by the corresponding axis (eigenvector);
- If the points on the graph tend to level out (show an "elbow" shape), these eigenvalues are usually close enough to zero that they can be ignored.
- In general: Limit the variance accounted for.





Determining the number of components $\mathbf{x}_i \in \mathfrak{R}^q$, $i = 1, \dots, N$ $\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_q$; q eigenvectors (principal component directions) $\|\mathbf{w}_i\| = 1$ (the \mathbf{w}_i s are orthonormal vectors) Representation of \mathbf{x}_i in eigenvector space : $\mathbf{y}_i = (\mathbf{w}_1^T \mathbf{x}_i)\mathbf{w}_1 + (\mathbf{w}_2^T \mathbf{x}_i)\mathbf{w}_2 + \dots + (\mathbf{w}_q^T \mathbf{x}_i)\mathbf{w}_q$ Suppose we retain the first k principal components : $\mathbf{y}_i^k = (\mathbf{w}_1^T \mathbf{x}_i)\mathbf{w}_1 + (\mathbf{w}_2^T \mathbf{x}_i)\mathbf{w}_2 + \dots + (\mathbf{w}_k^T \mathbf{x}_i)\mathbf{w}_k$ Then : $\mathbf{y}_i - \mathbf{y}_i^k = (\mathbf{w}_{k+1}^T \mathbf{x}_i)\mathbf{w}_{k+1} + \dots + (\mathbf{w}_q^T \mathbf{x}_i)\mathbf{w}_q$

Determining the number of components

$$(\mathbf{y}_{i} - \mathbf{y}_{i}^{k})^{T} (\mathbf{y}_{i} - \mathbf{y}_{i}^{k}) = [(\mathbf{w}_{k+1}^{T}\mathbf{x}_{i})\mathbf{w}_{k+1} + \dots + (\mathbf{w}_{q}^{T}\mathbf{x}_{i})\mathbf{w}_{q}]^{T} [(\mathbf{w}_{k+1}^{T}\mathbf{x}_{i})\mathbf{w}_{k+1} + \dots + (\mathbf{w}_{q}^{T}\mathbf{x}_{i})\mathbf{w}_{q}] = \mathbf{w}_{k+1}^{T} (\mathbf{w}_{k+1}^{T}\mathbf{x}_{i})^{2} \mathbf{w}_{k+1} + \dots + \mathbf{w}_{q}^{T} (\mathbf{w}_{q}^{T}\mathbf{x}_{i})^{2} \mathbf{w}_{q} = (note \mathbf{w}_{i}^{T}\mathbf{w}_{j} = 0 \ \forall i \neq j \text{ since } \mathbf{w}_{i} \text{ and } \mathbf{w}_{j} \text{ are orthogonal vectors}) (\mathbf{w}_{k+1}^{T}\mathbf{x}_{i})^{2} \mathbf{w}_{k+1}^{T}\mathbf{w}_{k+1} + \dots + (\mathbf{w}_{q}^{T}\mathbf{x}_{i})^{2} \mathbf{w}_{q}^{T}\mathbf{w}_{q} = (\mathbf{w}_{k+1}^{T}\mathbf{x}_{i})^{2} + \dots + (\mathbf{w}_{q}^{T}\mathbf{x}_{i})^{2} = (\mathbf{w}_{k+1}^{T}\mathbf{x}_{i})(\mathbf{x}_{i}^{T}\mathbf{w}_{k+1}) + \dots + (\mathbf{w}_{q}^{T}\mathbf{x}_{i})(\mathbf{x}_{i}^{T}\mathbf{w}_{q}) = \mathbf{w}_{k+1}^{T}(\mathbf{x}_{i}\mathbf{x}_{i}^{T})\mathbf{w}_{k+1} + \dots + \mathbf{w}_{q}^{T}(\mathbf{x}_{i}\mathbf{x}_{i}^{T})\mathbf{w}_{q}$$



