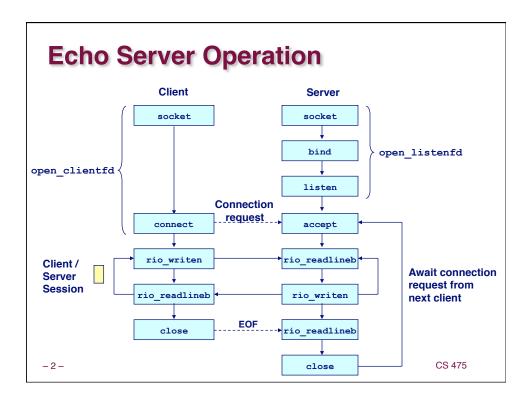
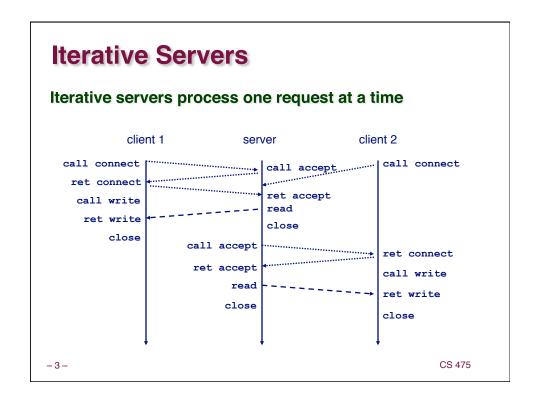
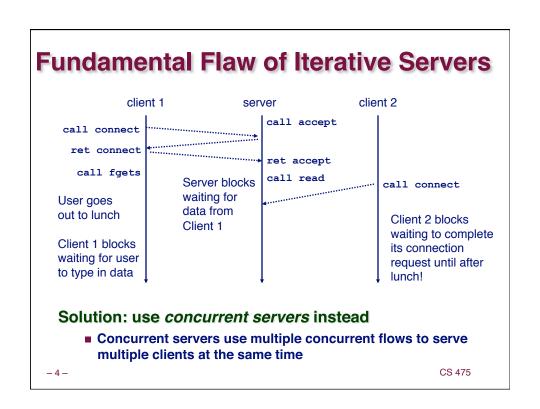
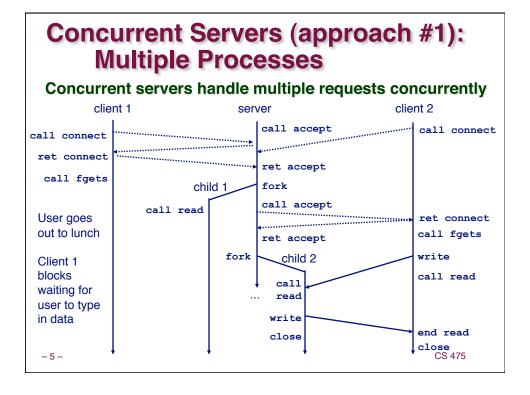


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Three Basic Mechanisms for Creating Concurrent Flows

1. Processes

- Kernel automatically interleaves multiple logical flows
- Each flow has its own private address space

2. Threads

- Kernel automatically interleaves multiple logical flows
- Each flow shares the same address space

3. I/O multiplexing with select()

- Programmer manually interleaves multiple logical flows
- All flows share the same address space
- Popular for high-performance server designs

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Review: Sequential Echo Server

```
int main(int argc, char **argv)
{
    int listenfd, connfd;
    int port = atoi(argv[1]);
    struct sockaddr_in clientaddr;
    int clientlen = sizeof(clientaddr);

    listenfd = Open_listenfd(port);
    while (1) {
        connfd = Accept(listenfd, (SA *)&clientaddr, &clientlen);
        echo(connfd);
        Close(connfd);
    }
    exit(0);
}
```

- Accept a connection request
- Handle echo requests until client terminates

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Process-Based Concurrent Server

```
int main(int argc, char **argv)
                                          Fork separate process for each
    int listenfd, connfd;
                                            client
   int port = atoi(argv[1]);
                                          Does not allow any
    struct sockaddr in clientaddr;
                                            communication between
    int clientlen=sizeof(clientaddr);
                                            different client handlers
    Signal(SIGCHLD, sigchld_handler);
    listenfd = Open_listenfd(port);
    while (1) {
       connfd = Accept(listenfd, (SA *) &clientaddr, &clientlen);
       if (Fork() == 0) {
           Close(listenfd); /* Child closes its listening socket */
                            /* Child services client */
           echo(connfd);
                            /* Child closes connection with client */
           Close(connfd);
           exit(0);
                             /* Child exits */
       Close (connfd); /* Parent closes connected socket (important!) */
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                                                                CS 475
```

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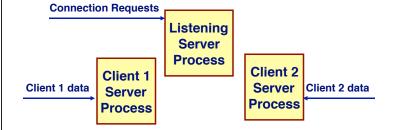
Process-Based Concurrent Server (cont)

```
void sigchld_handler(int sig)
{
    while (waitpid(-1, 0, WNOHANG) > 0)
    ;
    return;
}
```

Reap all zombie children

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Process Execution Model



- Each client handled by independent process
- No shared state between them
- When child created, each have copies of listenfd and connfd
 - Parent must close connfd, child must close listenfd

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Implementation Must-dos With Process-Based Designs

Listening server process must reap zombie children

■ to avoid fatal memory leak

Listening server process must close its copy of connfd

- Kernel keeps reference for each socket/open file
- After fork, refcnt(connfd) = 2
- Connection will not be closed until refcnt(connfd) == 0

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Pros and Cons of Process-Based Designs

- + Handle multiple connections concurrently
- + Clean sharing model
 - descriptors (no)
 - file tables (yes)
 - global variables (no)
- + Simple and straightforward
- Additional overhead for process control
- Nontrivial to share data between processes
 - Requires IPC (interprocess communication) mechanisms
 - FIFO's (named pipes), System V shared memory and semaphores

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Approach #2: Multiple Threads

Very similar to approach #1 (multiple processes)

but, with threads instead of processes

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A Process With Multiple Threads Multiple threads can be associated with a process Each thread has its own logical control flow ■ Each thread shares the same code, data, and kernel context Share common virtual address space (inc. stacks) ■ Each thread has its own thread id (TID) Thread 2 (peer thread) Thread 1 (main thread) Shared code and data shared libraries stack 1 stack 2 run-time heap read/write data Thread 1 context: Thread 2 context: Data registers read-only code/data Data registers **Condition codes Condition codes** SP1 SP2 PC₁ PC2 **Kernel context: VM structures Descriptor table** brk pointer CS 475 **- 14 -**

Thread-Based Concurrent Echo Server

```
int main(int argc, char **argv)
{
    int port = atoi(argv[1]);
    struct sockaddr_in clientaddr;
    int clientlen=sizeof(clientaddr);
    pthread_t tid;

    int listenfd = Open_listenfd(port);
    while (1) {
        int *connfdp = Malloc(sizeof(int));
        *connfdp = Accept(listenfd, (SA *) &clientaddr, &clientlen);
        Pthread_create(&tid, NULL, echo_thread, connfdp);
    }
}
```

- Spawn new thread for each client
- Pass it copy of connection file descriptor
- Note use of Malloc()!

Without corresponding Free()

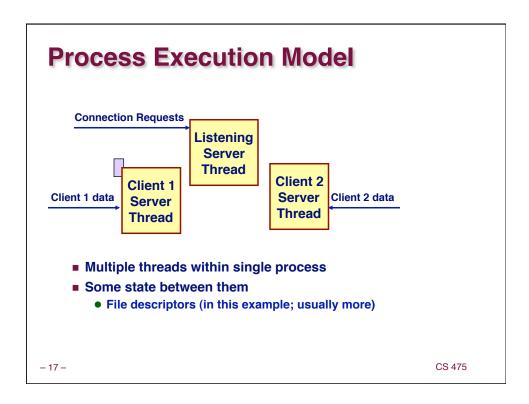
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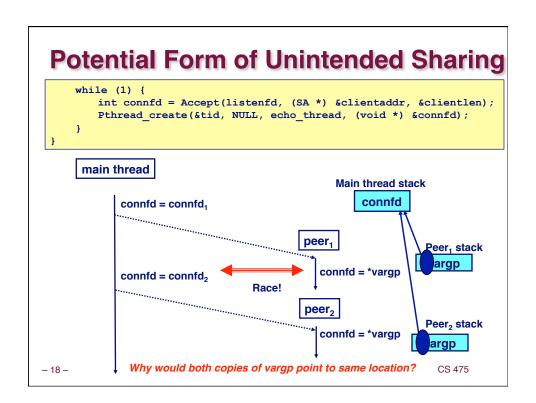
Thread-Based Concurrent Server (cont)

```
/* thread routine */
void *echo_thread(void *vargp)
{
   int connfd = *((int *)vargp);
   Pthread_detach(pthread_self());
   Free(vargp);
   echo(connfd);
   Close(connfd);
   return NULL;
}
```

- Run thread in "detached" mode
 - Runs independently of other threads
 - Reaped when it terminates
- Free storage allocated to hold clientfd
 - "Producer-Consumer" model

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Issues With Thread-Based Servers

Must run "detached" to avoid memory leak

- At any point in time, a thread is either joinable or detached
- Joinable thread can be reaped and killed by other threads
 - must be reaped (with pthread_join) to free memory resources
- Detached thread cannot be reaped or killed by other threads
 - resources are automatically reaped on termination
- Default state is joinable
 - use pthread detach(pthread self()) to make detached

Must be careful to avoid unintended sharing.

- For example, what happens if we pass the address of connfd to the thread routine?
 - Pthread_create(&tid, NULL, thread, (void
 *)&connfd);

All functions called by a thread must be thread-safe

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Pros and Cons of Thread-Based Designs

- + Easy to share data structures between threads
 - e.g., logging information, file cache
- + Threads are more efficient than processes
- --- Unintentional sharing can introduce subtle and hard-to-reproduce errors!
 - The ease with which data can be shared is both the greatest strength and the greatest weakness of threads

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Appr. #3: Event-Based Concurrent Servers Using I/O Multiplexing

Maintain a pool of connected descriptors

Repeat the following forever:

- Use the Unix select function to block until:
 - (a) New connection request arrives on the listening descriptor
 - (b) New data arrives on an existing connected descriptor
- If (a), add the new connection to the pool of connections
- If (b), read any available data from the connection
 - Close connection on EOF and remove it from the pool

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The select Function

select() sleeps until one or more file descriptors in the set readset
are ready for reading

```
#include <sys/select.h>
int select(int maxfdp1, fd_set *readset, NULL, NULL, NULL);
```

readset

- Opaque bit vector (max FD_SETSIZE bits) that indicates membership in a descriptor set
- If bit k is 1, then descriptor k is a member of the descriptor set

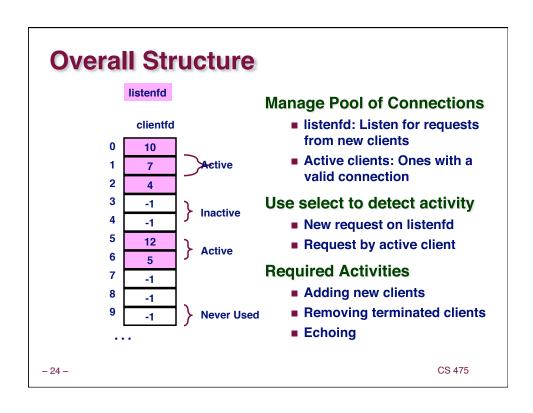
maxfdp1

- · Maximum descriptor in descriptor set plus 1
- Tests descriptors 0, 1, 2, ..., maxfdp1 1 for set membership

select() returns the number of ready descriptors and sets each bit of readset to indicate the ready status of its corresponding descriptor

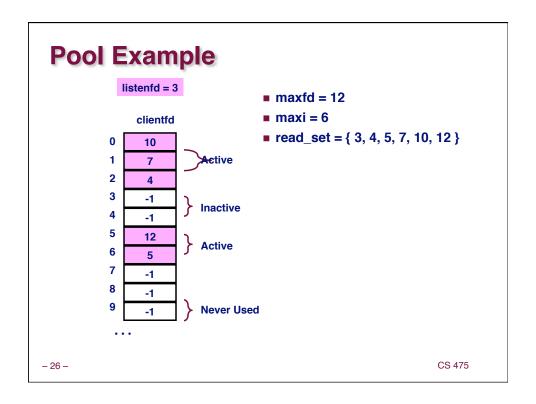
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Macros for Manipulating Set Descriptors



Representing Pool of Clients

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Main Loop

```
int main(int argc, char **argv)
     int listenfd, connfd, clientlen = sizeof(struct sockaddr_in);
     struct sockaddr_in clientaddr;
     static pool pool;
     listenfd = Open_listenfd(argv[1]);
     init pool(listenfd, &pool);
     while (1) {
         pool.ready_set = pool.read_set;
         pool.nready = Select(pool.maxfd+1, &pool.ready_set,
                              NULL, NULL, NULL);
         if (FD_ISSET(listenfd, &pool.ready_set)) {
             connfd = Accept(listenfd, (SA *)&clientaddr,&clientlen);
             add_client(connfd, &pool);
         check_clients(&pool);
                                                               CS 475
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```

Pool Initialization

```
/* initialize the descriptor pool */
void init_pool(int listenfd, pool *p)
{
    /* Initially, there are no connected descriptors */
    int i;
    p->maxi = -1;
    for (i=0; i< FD_SETSIZE; i++)
        p->clientfd[i] = -1;

    /* Initially, listenfd is only member of select read set */
    p->maxfd = listenfd;
    FD_ZERO(&p->read_set);
    FD_SET(listenfd, &p->read_set);
}
```

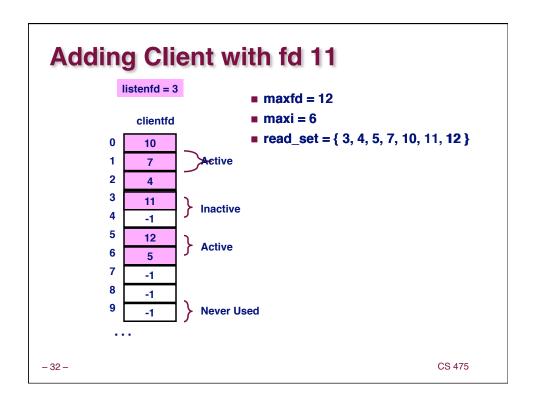
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```
Initial Pool
             listenfd = 3
                                      ■ maxfd = 3
                                      ■ maxi = -1
                clientfd
                                      read_set = { 3 }
           0
           1
                 -1
           2
                 -1
           3
                 -1
           4
                 -1
           5
                 -1
                         Never Used
           6
                 -1
           7
                 -1
           8
                 -1
           9
                 -1
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                                                                    CS 475
```

Main Loop

```
int main(int argc, char **argv)
     int listenfd, connfd, clientlen = sizeof(struct sockaddr_in);
     struct sockaddr in clientaddr;
     static pool pool;
     listenfd = Open listenfd(argv[1]);
     init_pool(listenfd, &pool);
     while (1) {
         pool.ready_set = pool.read_set;
         pool.nready = Select(pool.maxfd+1, &pool.ready_set,
                              NULL, NULL, NULL);
         if (FD_ISSET(listenfd, &pool.ready_set)) {
             connfd = Accept(listenfd, (SA *)&clientaddr,&clientlen);
             add_client(connfd, &pool);
         check_clients(&pool);
                                                              CS 475
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```

Adding Client



Checking Clients

```
void check_clients(pool *p) { /* echo line from ready descs in pool p */
   int i, connfd, n;
    char buf[MAXLINE];
   rio t rio;
    for (i = 0; (i \le p-\max i) \&\& (p-nready > 0); i++) {
        connfd = p->clientfd[i];
       rio = p->clientrio[i];
        /* If the descriptor is ready, echo a text line from it */
        if ((connfd > 0) && (FD_ISSET(connfd, &p->ready_set))) {
           p->nready--;
            if ((n = Rio_readlineb(&rio, buf, MAXLINE)) != 0) {
                byte cnt += n;
                Rio_writen(connfd, buf, n);
            else {/* EOF detected, remove descriptor from pool */
                Close(connfd);
                FD CLR(connfd, &p->read set);
                p->clientfd[i] = -1;
       }
    }
```

Concurrency Limitations

```
if ((connfd > 0) && (FD_ISSET(connfd, &p->ready_set))) {
    p->nready_-;
    if ((n = Rio_readlineb(&rio, buf, MAXLINE)) != 0) {
        byte_cnt += n;
        Rio_writen(connfd, buf, n);
    }
}
```

Does not return until complete line received

- Current design will gets stuck if partial line transmitted
- Bad to have network code that can get stuck if client does something weird
 - By mistake or maliciously
- Would require more work to implement more robust version
 - Must allow each read to return only part of line, and reassemble lines within server

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Pro and Cons of Event-Based Designs

- + One logical control flow
- + Can single-step with a debugger
- + No process or thread control overhead
 - Design of choice for high-performance Web servers and search engines
- Significantly more complex to code than process- or thread-based designs
- Hard to provide fine-grained concurrency
 - E.g., our example will hang up with partial lines

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Approaches to Concurrency

Processes

- Hard to share resources: Easy to avoid unintended sharing
- High overhead in adding/removing clients

Threads

- Easy to share resources: Perhaps too easy
- Medium overhead
- Not much control over scheduling policies
- Difficult to debug
 - Event orderings not repeatable

I/O Multiplexing

- Tedious and low level
- Total control over scheduling
- Very low overhead
- Cannot create as fine grained a level of concurrency

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